

# Teddy Herrera

herrera.teddy45@gmail.com | <https://github.com/teddyherrera> | [linkedin.com/in/teddy-herrera](https://www.linkedin.com/in/teddy-herrera)

## **OBJECTIVE**

As a Marine Corps Officer, I led in demanding environments and gained extensive technical and leadership experience. I am interested in trajectory optimization, navigation, and optimal and nonlinear control methods for autonomous systems.

## **EDUCATION**

**M.S. in Electrical Engineering**, Naval Postgraduate School **GPA: 3.85/4.0** Sept 2025

Specialties: **Signal Processing, Radar/Sensors/Electronic Warfare, Robotics**

Thesis: **3D Point Cloud Generation using Interferometric Synthetic Aperture Radar (SAR) for Target Recognition**

**B.S. in Mechanical Engineering**, New Mexico State University **GPA: 3.24/4.0** May 2019

Senior Design Project: **Smart Wearable Sensors for Motion Tracking** – link to presentation: <https://bit.ly/3YK1xiR>

## **EXPERIENCE**

**United States Marine Corps**, Captain (Air Support Control Officer & Electronics Engineer) June 2019 – Present

- Performed trade studies and provided technical recommendations for emerging and existing energy and power technologies as the Expeditionary Energy Officer at Marine Corps Systems Command.
- Supported 14 Service-level exercises that deployed detachments of 50-100 Marines and Sailors and millions of dollars of equipment across the West Coast.
- Deployed to Darwin, Australia in 2022. Conducted planning for multiple coalition field exercises and lead a small, mobile command and control team of 10-12 Marines.

**NASA Jet Propulsion Laboratory**, Mechanical Engineering Intern

May 2018 – Aug 2018

**Mission:** Perseverance Rover - Chassis Subsystem

Jan 2017 – July 2017

- Coordinated thermal vacuum bakeout of all Perseverance Rover Chassis components and assemblies, adhering to planetary protection and contamination and control guidelines.
- Performed testing of a deployable mechanism and documented the results under nominal, failure, and environmental conditions.
- Optimized component designs using Unigraphics NX and applied Geometric Dimensioning and Tolerancing ASME Y14.5 to engineering drawings.
- Worked hands-on with an engineer and flight technician to fabricate composite materials for the Rover heat exchangers.

## **SCHOLARSHIPS & AWARDS**

**Third Place, Best Engineering Design Award**, 2019 ExCEllence in Senior Design Showcase at UT Dallas May 2019

- Placed 3rd out of 14 senior design projects from universities across Texas, Arizona, and New Mexico.

**2014 Daniels Scholar**, Daniels Fund Scholarship Program Recipient May 2014

- The Daniels Scholarship covers the full cost of attendance for high school seniors who have demonstrated exceptional character, leadership, and a commitment to serving their communities, and who the value of founder Bill Daniels.

## **PROJECTS**

**Magnetic Navigation for Unmanned Aerial Systems**, Naval Postgraduate School | PI: Dr. Isaac Kaminer

- Using an Extended Kalman Filter with noisy simulated scalar magnetometer data, I evaluated multiple A\* cost functions to generate nonintuitive, highly observable magnetic-navigation trajectories, achieving a ~20% reduction in RMSE compared to straight line paths.

## **PUBLICATIONS**

Herrera, T. and D. A. Garren. "3D point cloud generation using interferometric synthetic aperture radar (SAR) for target recognition." Algorithms for Synthetic Aperture Radar Imagery XXXII. Vol. 13456. SPIE, 2025. Available: <https://doi.org/10.1117/12.2663642>